Zone Routing Protocol

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Abstract—Routing protocols for mobile ad-hoc networks have to face the challenge of frequently changing topology, low transmission power and asymmetric links. Both proactive and reactive routing protocols prove to be inefficient under these circumstances. The Zone Routing Protocol (ZRP) combines the advantages of the proactive and reactive approaches by maintaining an up-to-date topological map of a zone centered on each node. Within the zone, routes are immediately available. For destinations outside the zone, ZRP employs a route discovery procedure, which can benefit from the local routing information of the zones. This paper presents the Zone Routing Protocol. First, we discuss the problem of routing in ad-hoc networks and the motivation of ZRP. We describe the architecture of ZRP, which consists of three sub-protocols. We describe the routing process and illustrate it with an example. Further, we describe the query control mechanisms, which are used to reduce the traffic amount in the route discovery procedure. ZRP does not define the actual implementation of the protocol components. Therefore, we present the guidelines for implementation, and example implementations provided in the draft specifications. We discuss the problem of routing in networks with unidirectional links and the proposal for a solution to it. The overhead of the routing protocol is important in the power and bandwidth limited ad-hoc networks. We discuss the factors influencing the traffic amount based on measurements performed in a number of papers. We describe the significant issue of choosing an optimal zone radius, and two algorithms for automatic selection of the radius. Finally, we draw some conclusions about the performance of the protocol. The paper is based on literature research.

Keywords -- Wireless Network, Routing Protocol Technique, VANET

I.   INTRODUCTION

Ad-hoc networks are mobile wireless networks that have no fixed infrastructure. There are no fixed routers – instead each node acts as a router and forwards traffic from other nodes. Ad-hoc networks were first mainly used for military applications. Since then, they have become increasingly more popular within the computing industry. Applications include emergency search-and- rescue operations, deployment of sensors, conferences, exhibitions, virtual classrooms and operations in environments where construction of infrastructure is difficult or expensive. Ad-hoc networks can be rapidly deployed because of the lack of infrastructure. [2] [16] A MANET (Mobile Ad-hoc Network) is a type of ad- hoc network with rapidly changing topology. These networks typically have a large span and connect hundreds to thousands of nodes [16]. Correspondingly, the term Reconfigurable Wireless Networks (RWN) refers to large ad-hoc networks that can be rapidly deployed without infrastructure and where the nodes are highly mobile [14].   In this paper, we concentrate on routing in large ad-hoc networks with high mobility. Since the nodes in a MANET are highly mobile, the topology changes frequently and the nodes are dynamically connected in an arbitrary manner. The rate of change depends on the velocity of the nodes. Moreover, the devices are small and the available transmission power is limited. Consequently, the radio coverage of a node is small. The low transmission power limits the number of neighbor nodes, which further increases the rate of change in the topology as the node moves. Because of interference and fading due to high operating frequency in an urban environment, the links are unreliable. Ad-hoc networks are further characterized by low bandwidth links. Because of differences in transmission capacity, some of the links may be unidirectional. As a result of link instability and node mobility, the topology changes frequently and routing is difficult.

II.   ROUTING IN AD-HOC NETWORKS

A number of routing protocols have been suggested for ad-hoc networks [2]. These protocols can be classified into two main categories: proactive (table-driven) and reactive (source-initiated or demand-driven).

Proactive routing protocols attempt to keep an up-to-date topological map of the entire network. With this map, the route is known and immediately available when a packet needs to be sent. The approach is similar to the one used in wired IP networks, for example in OSPF [3]. [1]

Proactive protocols are traditionally classified as either distance-vector or link-state protocols. The former are based on the distributed Bellman-Ford (DBP) algorithm, which is known for slow convergence because of the "counting-to-infinity" problem. To address the problem, the Destination-Sequenced Distance-Vector routing (DSDV) [4] protocol was proposed for ad-hoc networks. On the other hand, link-state

protocols, as represented by OSPF [3], have become standard in wired IP networks. They converge more rapidly, but require significantly more control traffic. Since ad-hoc networks are bandwidth limited and their topology changes often, an Optimized Link-State Protocol (OLSR) [5] has been proposed. While being suitable for small networks, some scalability problems can be seen on larger networks. The need to improve convergence and reduce traffic has led to algorithms that combine features of distance-vector prescribed, although the various and link-state schemes. Such a protocol is the wireless routing protocol (WRP) [6], which eliminates the counting-to-infinity problem and avoids temporary loop without increasing the amount of control traffic.

In contrast to proactive routing, reactive routing does not attempt to continuously determine the network connectivity. Instead, a route determination procedure is invoked on demand when a packet needs to be forwarded. The technique relies on queries that are flooded throughout the network.

Reactive route determination is used in the Temporally Ordered Routing Algorithm (TORA) [7], the Dynamic Source Routing (DSR) [8] and the Ad-hoc On-demand Distance Vector (AODV) protocols. In DSR and AODV, a reply is sent back to the query source along the reverse path that the query traveled. The main difference is that DSR performs source routing with the addresses obtained from the query packet, while AODV uses next-hop information stored in the nodes of the route. In contrast to these protocols, TORA creates directed acyclic graphs rooted at the destination by flooding the route replies in a controlled manner.

Comparison of proactive and reactive routing

Both proactive and reactive routing have specific advantages and disadvantages that make them suitable for certain types of scenarios. Since proactive routing maintains information that is immediately available, the delay before sending a packet is minimal. On the contrary, reactive protocols must first determine the route, which may result in considerable delay if the information is not available in caches. Moreover, the reactive route search procedure may involve significant control traffic due to global flooding. This, together with the long setup delay, may make pure reactive routing less suitable for real-time traffic. However, the traffic amount can be reduced by employing route maintenance schemes. [10]Purely proactive schemes use a large portion of the bandwidth to keep routing information up-to-date. Because of fast node mobility, the route updates may be more frequent than the route requests, and most of the routing information is never used. Some of the scarce bandwidth is thus wasted.
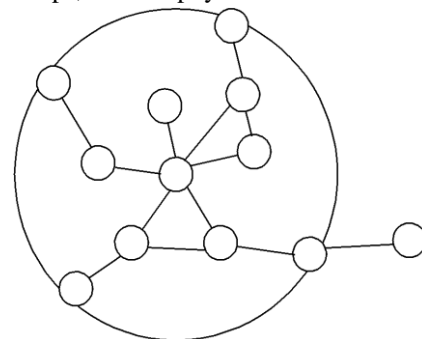
III. THE ZONE ROUTING PROTOCOL

Motivation

As seen, proactive routing uses excess bandwidth to maintain routing information, while reactive routing involves long route request delays. Reactive routing also inefficiently floods the entire network for route determination. The Zone Routing Protocol (ZRP) [11] – [13] aims to address the problems by combining the best properties of both approaches. ZRP can be classed as a hybrid reactive/proactive routing protocol. In an ad-hoc network, it can be assumed that the largest part of the traffic is directed to nearby nodes. Therefore, ZRP reduces the proactive scope to a zone centered on each node. In a limited zone, the maintenance of routing information is easier. Further, the amount of routing information that is never used is minimized. Still, nodes farther away can be reached with reactive routing. Since all nodes proactively store local routing information, route requests can be more efficiently performed without querying all the network nodes. Despite the use of zones, ZRP has a flat view over the network. In this way, the organizational overhead related to hierarchical protocols can be avoided. Hierarchical routing protocols depend on the strategic assignment of gateways or landmarks, so that every node can access all levels, especially the top level. Nodes belonging to different subnets must send their communication to a subnet that is common to both nodes. This may congest parts of the network. ZRP can be categorized as a flat protocol because the zones overlap. Hence, optimal routes can be detected and network congestion can be reduced. Further, the behavior of ZRP is adaptive. The behavior depends on the current configuration of the network and the behavior of the users.

Architecture

The Zone Routing Protocol, as its name implies, is based on the concept of zones. A routing zone is defined for each node separately, and the zones of neighboring nodes overlap. The routing zone has a radius expressed in hops. The zone thus includes the nodes, whose distance from the node in question is at most hops. An example routing zone is shown in Figure 1, where the routing zone of S includes the nodes A–I, but not K. In the illustrations, the radius is marked as a circle around the node in question. It should however be noted that the zone is defined in hops, not as a physical distance.

The nodes of a zone are divided into peripheral nodes and interior nodes. Peripheral nodes are nodes whose minimum distance to the central node is exactly equal to the zone radius ⍴. The nodes whose minimum distance is less than ⍴ are interior nodes. In Figure 1, the nodes A–F are interior nodes, the nodes G–J are peripheral nodes and the node K is outside the routing zone. Note that node H can be reached by two paths, one with length 2 and one with length 3 hops. The node

is however within the zone, since the shortest path is less than or equal to the zone radius. ZRP refers to the locally proactive routing component as the Intra-zone Routing Protocol (IARP). The globally reactive routing component is named Inter-zone Routing Protocol (IERP). IERP and IARP are not specific routing protocols. Instead, IARP is a family of limited-depth, proactive link-state routing protocols. IARP maintains routing information for nodes that are within the routing zone of the node. Correspondingly, IERP is a family of reactive routing protocols that offer enhanced route discovery and route maintenance services based on local connectivity monitored by IARP. Instead of broadcasting packets, ZRP uses a concept called bordercasting. Bordercasting utilizes the topology information provided by IARP to direct query request to the border of the zone. The bordercast packet delivery service is provided by the Bordercast Resolution Protocol (BRP). BRP uses a map of an extended routing zone to construct bordercast trees for the query packets. Alternatively, it uses source routing based on the normal routing zone. By employing query control mechanisms, route requests can be directed away from areas of the network that already have been covered. In order to detect new neighbor nodes and link failures, the ZRP relies on a Neighbor Discovery Protocol (NDP) provided by the Media Access Control (MAC) layer. NDP transmits "HELLO" beacons at regular intervals. Upon receiving a beacon, the neighbor table is updated. Neighbors, for which no beacon has been received within a specified time, are removed from the table. If the MAC layer does not include a NDP, the functionality must be provided by IARP. The relationship between the components is illustrated in Figure 2. Route updates are triggered by NDP, which notifies IARP when the neighbor table is updated. IERP uses the routing table of IARP to respond to route queries. IERP forwards queries with BRP. BRP uses the routing table of IARP to guide route queries away from the query source.

Routing

A node that has a packet to send first checks whether the destination is within its local zone using information provided by IARP. In that case, the packet can be routed proactively. Reactive routing is used if the destination is outside the zone. [13]

The reactive routing process is divided into two phases: the route request phase and the route reply phase. In the route request, the source sends a route request packet to its peripheral nodes using BRP. If the receiver of a route request packet knows the destination, it responds by sending a route reply back to the source. Otherwise, it continues the process by bordercasting the packet. In this way, the route request spreads throughout the network. If a node receives several copies of the same route request, these are considered as redundant and are discarded [12].The reply is sent by any node that can provide a route to the destination. To be able to send the reply back to the source node, routing information must be accumulated when the request is sent through the network. [13]The information is recorded either in the route request packet, or as next-hop addresses in the nodes along the path.

In the first case, the nodes forwarding a route request packet append their address and relevant node/link metrics to the packet. When the packet reaches the destination, the sequence of addresses is reversed and copied to the route reply packet. The sequence is used to forward the reply back to the source. In the second case, the forwarding nodes records routing information as next-hop addresses, which are used when the reply is sent to the source. This approach can save transmission resources, as the request and reply packets are smaller. [12]The source can receive the complete source route to the destination. Alternatively, the nodes along the path to the destination record the next-hop address in their routing table. [12]In the bordercasting process, the bordercasting node sends a route request packet to each of its peripheral nodes. This type of one-to-many transmission can be implemented as multicast to reduce resource usage. One approach is to let the source compute the multicast tree and attach routing instructions to the packet. This is called Root-Directed Bordercasting (RDB). Another approach is to reconstruct the tree at each node, whereas the routing instructions can be omitted. This requires that every interior node knows the topology seen by the bordercasting node. Thus, the nodes must maintain an extended routing zone with radius $2\square-1$ hops. Note that in this case the peripheral nodes where the request is sent are still at the distance $\square$. This approach is named Distributed Bordercasting (DB). [13] [15]

The zone radius is an important property for the performance of ZRP. If a zone radius of one hop is used, routing is purely reactive and bordercasting degenerates into flood searching. If the radius approaches infinity, routing is reactive. The selection of radius is a tradeoff between the routing efficiency of proactive routing and the increasing traffic for maintaining the view of the zone. [12]

Route maintenance

Route maintenance is especially important in ad-hoc networks, where links are broken and established as nodes move relatively to each other with limited radio coverage. In purely reactive routing protocols, routes containing broken links fail and a new route discovery or route repair must be performed. Until the new route is available, packets are dropped or delayed.

In ZRP, the knowledge of the local topology can be used for route maintenance. Link failures and sub-optimal route segments within one zone can be bypassed. Incoming packets can be directed around the broken link through an active multi-hop path. Similarly, the topology can be used to shorten routes, for example, when two nodes have moved within each other's radio coverage. For source-routed packets, a relaying node can determine the closest route to the destination that is also a neighbor. Sometimes, a multi-hop segment can be replaced by a single hop. If next-hop forwarding is used, the nodes can make locally optimal decisions by selecting a shorter path.

Determining the routing zone radius

With the correct zone size, it is possible to reduce the control traffic to a minimum. Each network configuration has an optimal zone radius value. To determine the optimal value, it is necessary to understand how different factors influence on the traffic amount. According to simulations performed in [10], the main factors are the zone radius ⬚, network size N, node density ⬚ (average number of neighbors per node) and average node velocity v (affecting route stability). Of these, only the zone radius is a configurable parameter.

Because of proactive route maintenance, the amount of control traffic from IARP increases with increasing zone radius. Since IARP route updates are a local event, the network size does not affect the amount of proactive traffic. The amount of IERP traffic received by a node is independent of N as well. Instead, an increase in the network size increases the number of route queries. Thus, the amount of reactive route query traffic increases with increasing network size. Therefore, larger zone sizes are favored in large networks. Larger zones provide more efficient queries, which compensates for the higher IARP maintenance costs.

The amount of control traffic largely depends on the relationship between node velocity and route usage. Higher velocity causes a linear increase in IARP routing updates and IERP route failures. If the route usage rate is considerably higher than the route failure rate, route discoveries are driven by route failures, and the traffic amount increases linearly with the node velocity. In contrast, if route usage is smaller than the route failure rate, the route query rate is independent of route stability and node velocity. In this case, the load on IARP increases with the node velocity, and a small routing zone is preferential. The optimal radius seems to independent of the node density in most cases. Yet, a large increase in the node density increases the cost of IARP routing zone maintenance, which decreases the optimal routing zone radius.

Zone sizing schemes

As seen, the optimal routing zone radius depends on a number of factors, which varies for different networks and also varies within a network as a function of time. Even with perfect knowledge of all parameters, computation of the optimal radius is complicated. Even though it is possible to estimate the node density, relative node velocity, network size, the performance also depends on other factors, such as route selection criteria, route caching policies and data traffic behavior. Therefore, the paper [10] proposes two zone sizing schemes.

The "min searching" scheme searches for a local minimum of the total ZRP traffic. The routing zone radius is either incremented or decremented in steps of one. The process is repeated in the same direction as long as the new measured traffic amount is smaller than the previous one. The found minimum is maintained until the process restarts later. The paper also suggests an automatic method for determining the time before the process is restarted. The local minimum that is found is also a global minimum since both the IARP and IERP traffic are convex functions of the zone radius. The

problem with this technique is that the estimation interval must be long enough to provide accurate measurements, but a long interval may not provide adequate correlation between consecutive intervals.

The other scheme is based on the relationship between IARP and IERP traffic. When the zone radius is less than the optimal and the ZRP traffic is more than optimal, the traffic is dominated by IERP queries. If the zone radius is larger than the optimal and the traffic is more than optimal, most of the traffic is IARP route updates. This property is used in the "traffic adaptive" scheme. The ratio of IERP and IARP traffic is compared with a threshold. The zone size is increased if IERP/IARP is larger than the threshold and reduced if less. A hysteresis value is used to improve stability. In this scheme only data collected from one measurement interval is used, which improves performance in frequently changing networks.

An oscillation problem may appear in the "traffic adaptive" scheme if the zone size is small. It is caused by the fact that a zone of radius one is purely reactive. To solve this problem, both the above schemes can be combined. The min searching scheme is then used when the radius is small (one or two hops) and the adaptive scheme is used otherwise.

IV. CONCLUSIONS

ZRP combines two completely different routing methods into one protocol. Within the routing zone, the proactive component IARP maintains up-to-date routing tables. Routes outside the routing zone are discovered with the reactive component IERP using route requests and replies. By combining bordercasting, query detection and early termination, it is possible to reduce the amount of route query traffic. Since the actual implementation of IARP and IERP is not defined, the performance can be further improved by adapting other routing protocols as ZRP components. ZRP can be regarded as a routing framework rather than as an independent protocol. ZRP reduces the traffic amount compared to pure proactive or reactive routing. Routes to nodes within the zone are immediately available. ZRP is able to identify multiple routes to a destination, which provides increased reliability and performance. It ensures that the routes are free from loops. It is a flat protocol, which reduces congestion and overhead usually related to hierarchical protocols. The zone routing protocol is targeted for large networks. It differs from cluster based routing protocols because the zones overlap. Because proactive updates are propagated only locally, the amount of control traffic does not depend on network size. The reactive routing is more efficient than flooding since local topology information can be used. Enlarging the zone size reduces the amount of reactive traffic. [10]

The protocol performance can be optimized by adjusting a single parameter, the zone radius. The parameter controls the tradeoff between the cost of the proactive and reactive components, which both are convex functions of the zone radius. The optimal zone radius depends on a number of

factors, including node velocity, node density and network span. Since these parameters changes, also the zone radius must be adjusted for optimal performance. Two methods for dynamically adjusting the zone radius have been examined in [10]. The "min searching" scheme keeps the traffic within 7% of the minimum traffic. The "traffic adaptive" scheme performs even better with traffic less than 1-2% than the optimal. The ZRP is defined in three separate Internet drafts: IARP in [11], IERP in [12] and BRP in [13]. ZRP is one of the protocols that are currently under evaluation and standardization by the IETF MANET working group. Since ZRP is more like a routing framework, it does not directly compete with other routing protocols. Most evaluations and comparisons of protocols for ad-hoc networks skip ZRP. The reason is usually that ZRP is aimed for larger networks than the test comprises, or that ZRP is not an independent protocol but rather a routing framework. Further, any evaluation of the ZRP version with support for unidirectional links could not be found. Tests made in [10] verify that ZRP with proper configuration of radius performs more efficiently than traditional routing protocols without need for centralized control. It is especially well adapted to large networks and diverse mobility patterns. Based on the evaluations studied in this paper, we can conclude that ZRP performs better than any single proactive or reactive protocol. This is especially true if we take into account that almost any pure proactive and reactive protocol can be adapted as an IARP or IERP component of ZRP. However, the cost of ZRP is increasing complexity, and in the cases where ZRP performs only slightly better than the pure protocol components, one can speculate whether the cost of added complexity outweigh the performance improvement. Furthermore, new protocols that are neither proactive nor reactive, as well as protocols utilizing geographical information may outperform the ZRP.

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